

Flight Test Results for Miniature GPS/Inertial Camera Payload

GNC MAS 2009 Miniature Multi-Function Seekers/Sensors 27 October 2009

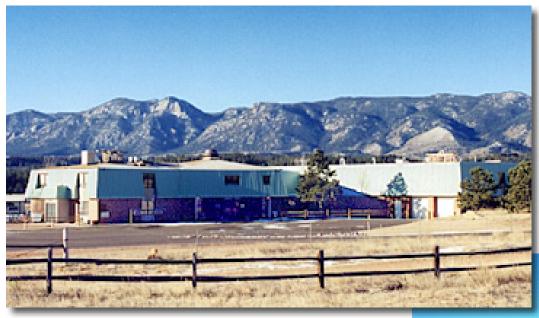
Reece Tredway and Alison Brown, NAVSYS Corporation Dr. Tom Lippmann, Dugout Consulting

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NAVSYS Corporation

Founded 1986



Provides specialized GPS products & services for our customers by leveraging our core technologies, unique technical expertise, innovative engineering, strong work ethic, and high standards of excellence

Tier 1 UAS GPS/IMU/Camera Payloads

Challenge

- DoD has an ever-increasing need for miniature, multifunction UAS platform sensors
 - Tier I UAS SWAP limitations present significant engineering challenge
 - Ability to positively identify and precisely locate military targets in real-time is a current shortfall with current Tier 1 UAS

Solution

- Small form-factor lightweight GPS/IMU Micro-Camera payload
 - Provides precision georegistered imagery
 - Moving capabilities currently available in larger Tier II payloads to the smaller UAS payloads

UAV Based Bathymetry/Mapping/Targeting/WUPT

- Capabilities Georegistered Imagery brings to the Warfighter
 - Targeting
 - StrikeLink Integration
 - Mapping
 - Military Mission Planners
 Near real-time targeting data/Bomb Damage Assessment
 - Low-cost Rapid Coastal Surveys
 - Precision Land Maps
 - Bathymetry
 - Army Corp of Engineers High resolution shoreline data for modeling for forecasting
 - Littoral Battlespace Sensing, Fusion, and Integration (LBSF&I)
 Bathymetry surveys critical for modeling & mission planning operations
 - Navy METOC Bathymetry data from shallow regions in support of littoral operations
 - Wave Modeling

• Flight Tests at US Air Force Academy

Targeting and Mapping Results



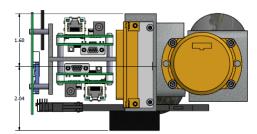


GI-Eye Systems

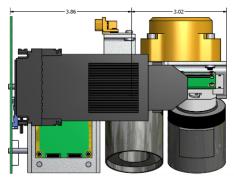




FLIR StarSAFIRE III



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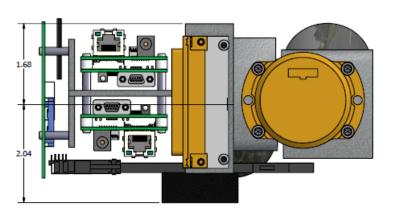
Micro-Camera (Dual Camera)

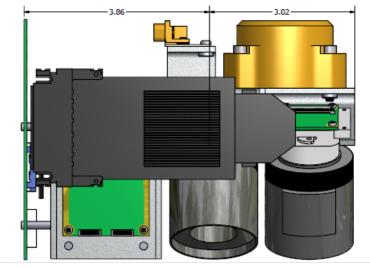
NGA Tactical Surveying and Targeting System (TS2)



Dual GI-Eye System Flown at USAFA

Micro-Camera Payload – Tier I





Features

•Operation

Interface

•Command

•Video Out

Electrical

•Supply Voltage •Power

Mechanical

•Size •Weight

Video •Payload Camera

Operating Envelope

- •Range
- •Speed
- •Operating Altitude

Data Processing

- •Bathymetry
- •Mapping

In-flight, fully autonomous flight planning

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Serial over UAV platform wireless link Serial over UAV platform wireless link

12 Volts 10 W (typical)

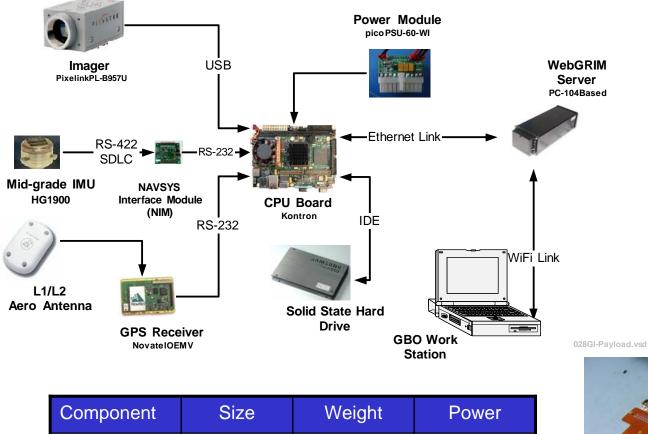
3.25" x 4" x 7" 900 grams / 2 lbs

Dual side looking 3.1 megapixel color machine vision imaging modules

Limited by UAV platform and available memory Up to 60 mph 500 – 1500 ft AGL

Post process data collected over littoral region Mapping capability from mosaicked imagery

UAS GI-Eye Payload



Component	Size	vveight	Power
As shown above	~ 300 Cubic Inches	~ 9 lbs	~ 175 Watts

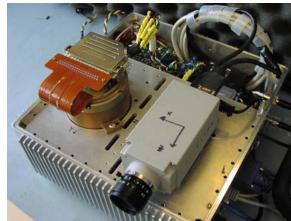
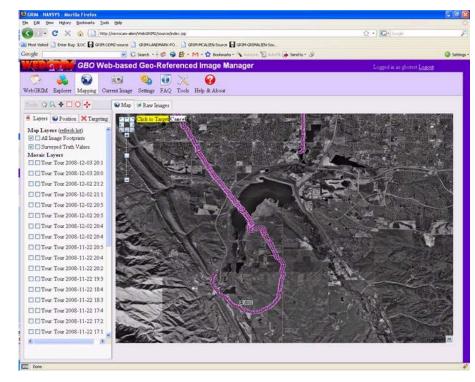


Image Management



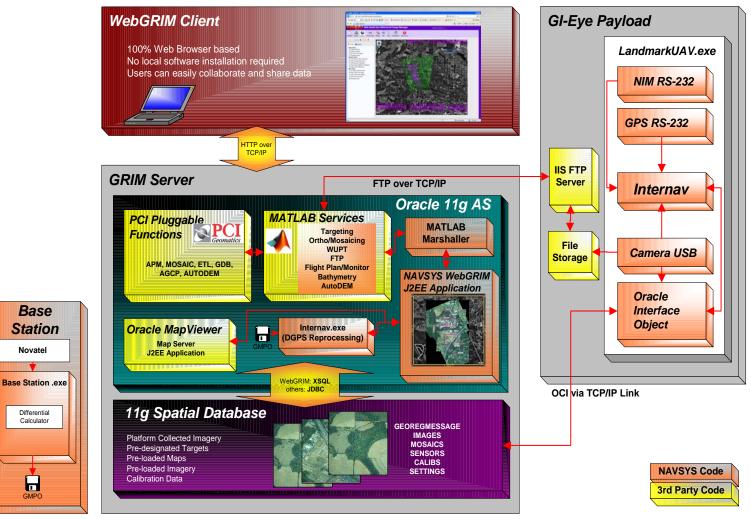
WebGRIM Ground Station Software

- Web Based
 - No new software to install
 - On-line collaboration between multiple
 users
- Quickly locate & manipulate collected imagery
 - Orthorectification & mosaicking
 - Point and click targeting
- User Customized Tools
 - UAV Flight planning
 - Bathymetry map generation
 - Targeting
 - Auto-DEM generation from collected imagery
- OGC Compliant
 - Display third party maps
 - Acts as Web Mapping Service



WebGRIM Server

Overall Web-based Georeferrenced Image Manager (WebGRIM) Architecture



USAFA Flight Test - 11 July 09

- Rocky Mountain Aerial Surveys, Inc Cessna 206G
 - Based in Denver
- Collection Area
 - Northeast section of USAFA
 - 25 NGA surveyed Ground Control Points
- Landmark Payload
 - 1 Hz images, looking Nadir
- Micro-Camera Payload
 - 2 Hz images, 30 degrees off Nadir
- Post processed images used to:
 - Test single and multi-shot targeting through WebGRIM
 - Collect imagery for AutoDEM processing and mapping
 - Validate WUPT navigation algorithms









StrikeLink/WebGRIM Integration

UAS Based Targeting

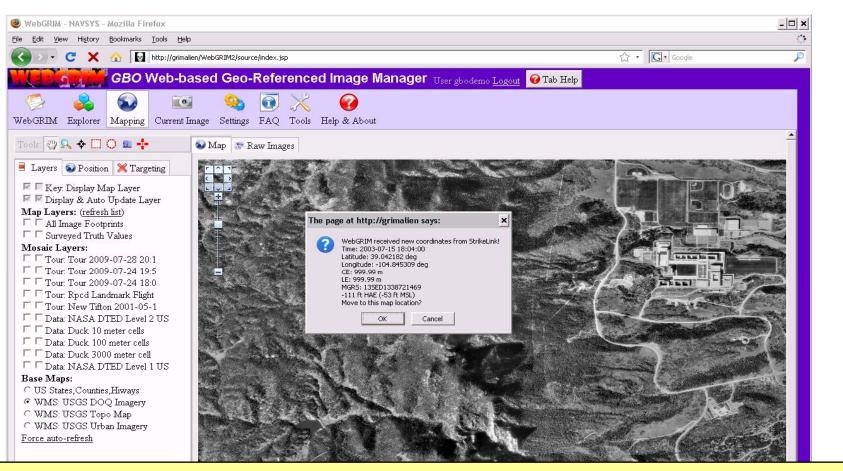
2PC - WGS 1984: Global Definition -	- [Map1 - Vector]	- 8 ×
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StrikeLink		
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On Call Inactive		
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	AD0019	
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	Target Properties x	
	Target Number: ADUUT9 Generic Type: UNKNOWN	7
	Deg Protection: Not Set	
	Location	
	MGR3: 135 ED 13387 21469 WGS-84	
	Range (M): Invalid Observer Horiz. Azimuth (Milit): Invalid Observer Mag	
	Elev (Ft-MSL) 56.31 More Elevation	
	Type Dimensions Point Reduce (M) 00	
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<u>v</u> v t	Attude (Mis) 6242.26 Mag	
Unknown N/A		
(Unk): N/A I/A	Locked 🙆 New Mission DK Cancel	

The user generates his target in StrikeLink in the usual fashion, and then clicks the PSS-SOF button. WebGRIM intercepts this COT XML message...



StrikeLink/WebGRIM Integration

UAS Based Targeting

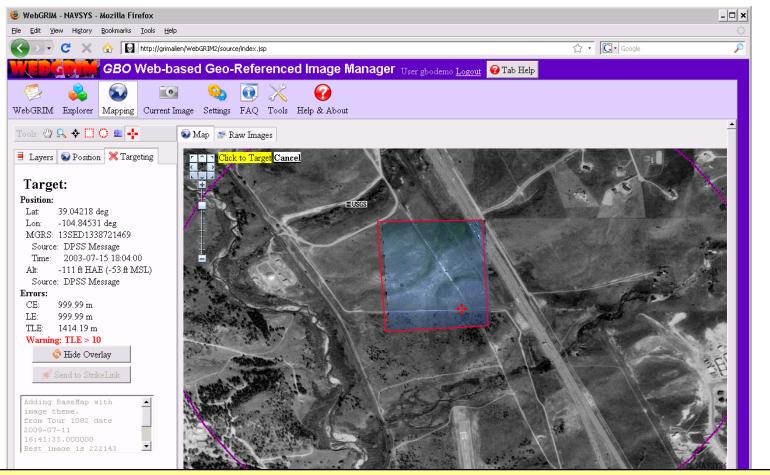


WebGRIM displays the StrikeLink coordinates and prompts user to move the map display

UAS Based Targeting



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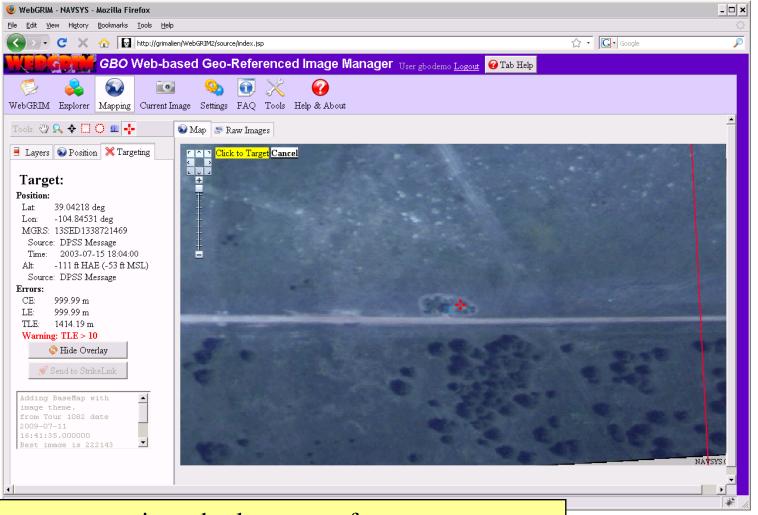


DPSS page displays red open cross targeting icon using the CoTXML coordinates on the background map with the most recent image from GI-Eye overlaid on the background map layer

UAS Based Targeting



Web Based DPSS Pages and StrikeLink Integration

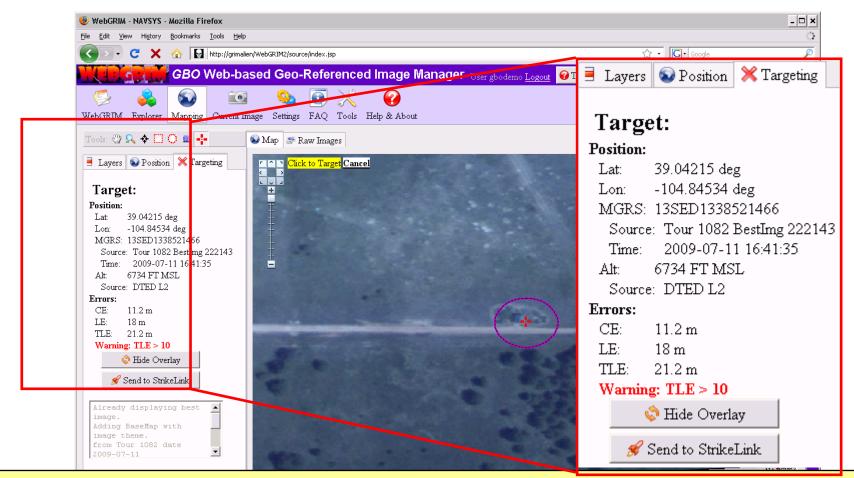


User can zoom in and select target feature

UAS Based Targeting



Web Based DPSS Pages & StrikeLink Integration



WebGRIM displays latitude longitude, & altitude & the corresponding CE, LE, & TLE. GBO can send LLA, CE & LE back to StrikeLink via CoTXML. If resolution or accuracy not sufficient, user continues on to raw images.



Back at StrikeLink...

UAS Based Targeting

E		
` J		
	Target Properties	
	Target Number: AD0019 Generic Type: UNKNOWN	
~	Num Elements: 1 Sub Type: Unknown Deg Protection: Not Set	
	ew Position Data	
	Action PSS-SDF Update Target AD0019 If you want to update an item not in the list, open its dialog and resend this location to StrikeLink MGRS: 135 ED 13387 21462 More	
	Range: Horiz. Azimuth: Elevation (Ft - MSL): 6713.843341	
ц.		

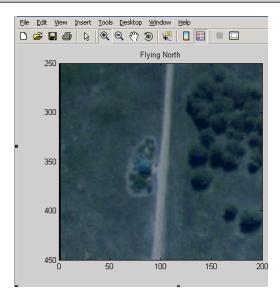
StrikeLink has received the updated coordinates for the target, and offers to modify it's target to match.

Single Shot Targeting Results

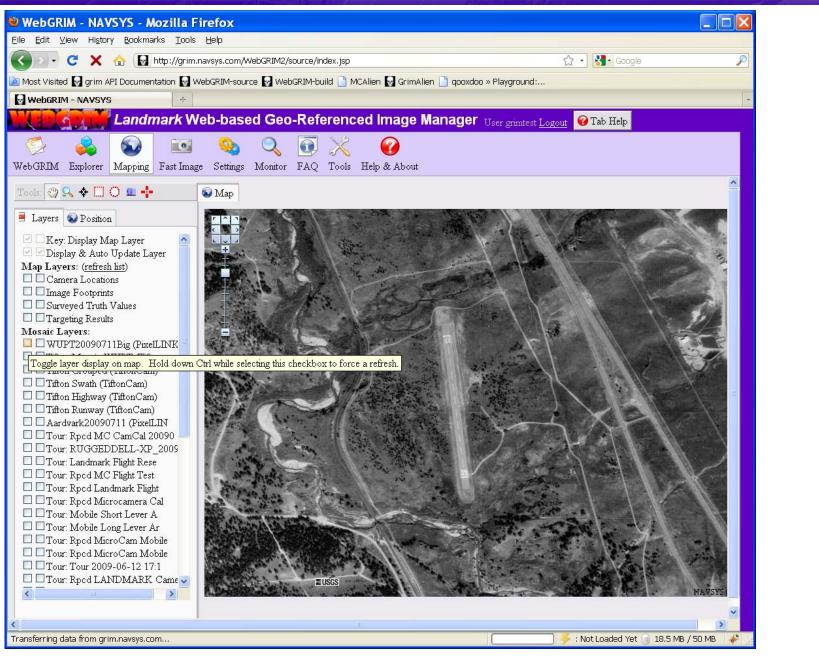
- Targeting Accuracy
 - Accuracy when flying at Tier I UAV Altitude ranges
 - DGPS post processed Wi-Fi link not available in test aircraft

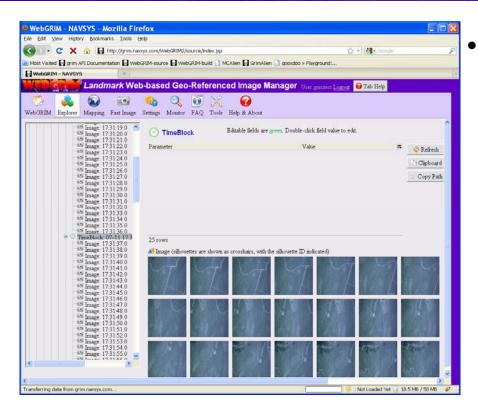
Image Time	Target ID	North Error	East Error	Down Error
576249	1	-0.26	1.98	-1.15
576250	1	-0.21	-0.83	-1.14
576251	1	1.35	-1.63	-1.14
576252	1	5.97	-2.324	-1.14
576236	2	-2.32	-0.51	2.13
576237	2	-2.78	-1.79	2.13
576238	2	-1.92	0.24	2.13
576239	2	-1.47	0.25	2.13
576240	2	1.85	-0.61	2.13
576241	2	2.21	-0.1	2.13
578502	2	-1.18	4.26	2.13
578503	2	-2.43	9.68	2.13
578504	2	-2.36	5.44	2.13
578505	2	-2.83	3.85	2.13
578506	2	-3.08	2.16	2.13
578507	2	-2.83	-2	2.13
	RMS			
	(m)	2.54	3.37	1.93

<u>File Edit View Insert Tools Desktop Window Help</u> 🗅 😅 🖬 🎒 💊 🔍 🍳 🖑 🕲 🐙 📘 📰 💷 VR\Apache\Apache\htdocs\GRIMX\IMAGES\Tour2123\Sensor422\\141_161





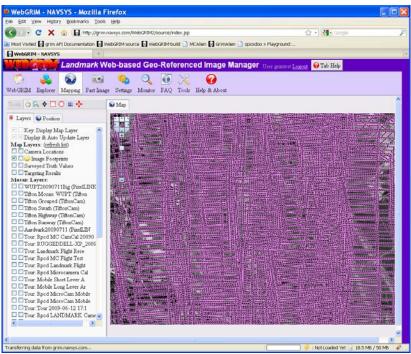


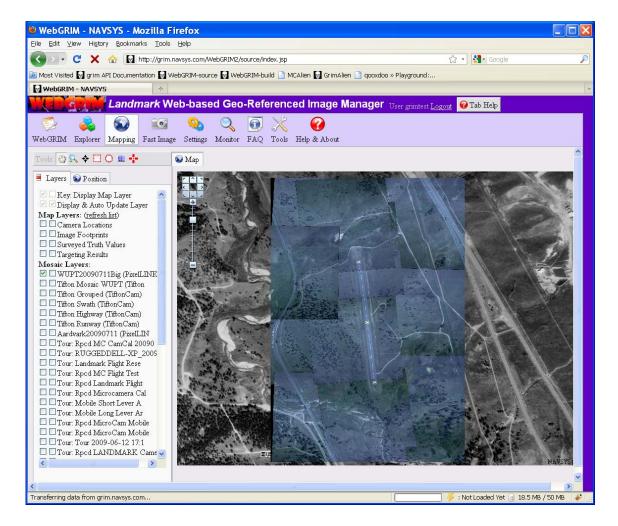


- Image management software
 - Single flight test generates 1000's of images

DAVS

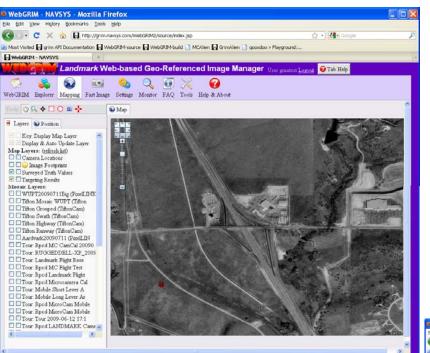
Manual image selection not possible





- Map Creation
 - WebGRIM software selects images that overlay user AOI

 Imagery loaded into single GeoRaster to create map mosaic

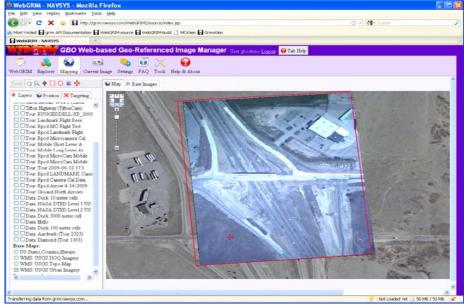


: Not Loaded Vet 👔 18.5 MB / 50 MB 🛛 💞

- Time-Sensitive Layer
 - USGS Background Map

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New bridge construction



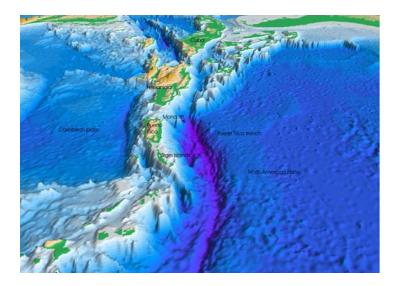
UAS Based Bathymetry

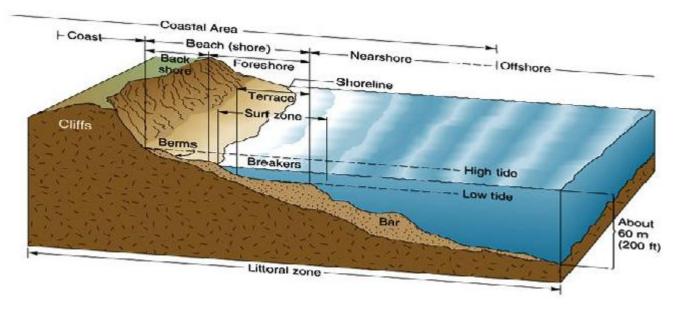


Bathymetry Underwater equivalent to topography

Littoral Zone

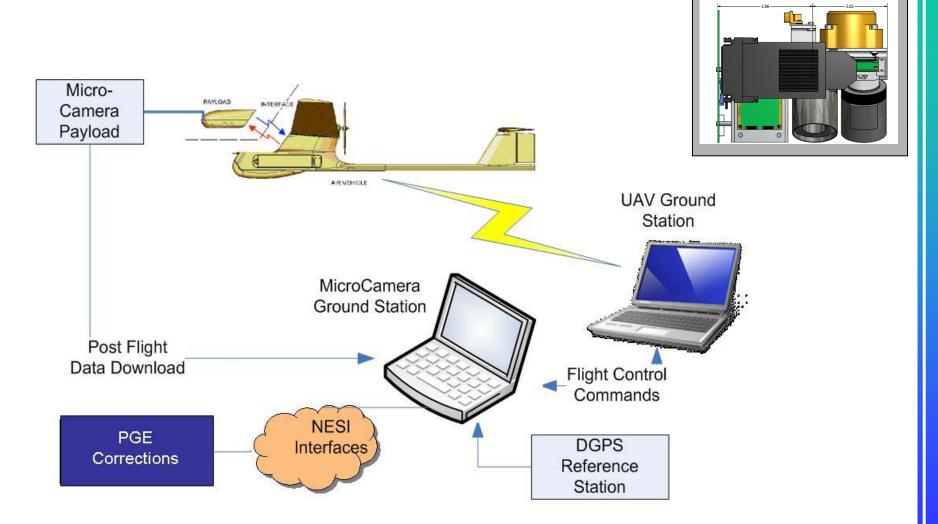
Permanently submerged ocean region extending from high water mark to shoreline areas







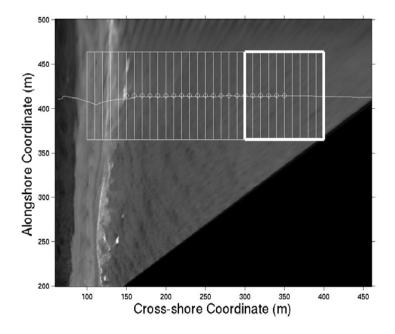
NAVSYS Micro-Camera

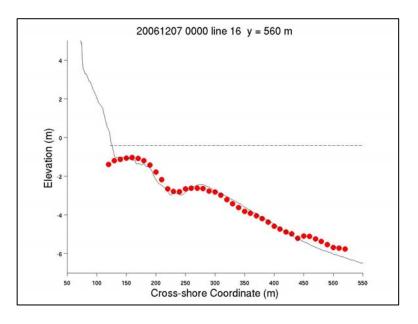


UAS Based Bathymetry



- Computer software for estimating water depth in shallow regions (0.5 - 30 m) from time series of airborne imagery
- Uses spectral (FFT) inversion techniques based on the physics of surface gravity waves
- Presently MATLAB code → C-coded GUI





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Summary

• Tier 1 UAS

Mapping

Targeting

• Bathymetry

Georegistered Imagery



NAVS

20061207 0000 line 16 y = 560 m

